The Robo-RO Interface to USSTRATCOM: How to Do On-Demand All-Sky LGS AO Observations

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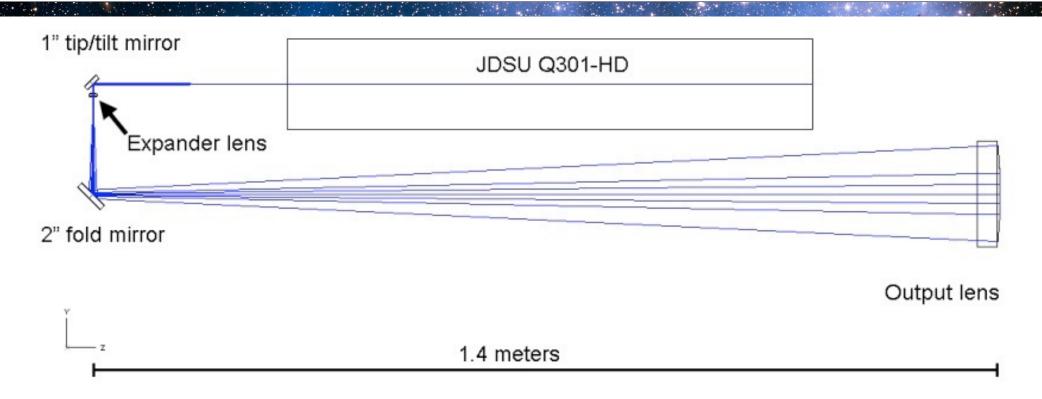
Center for Adaptive Optics 2014 Retreat November 17th, 2014







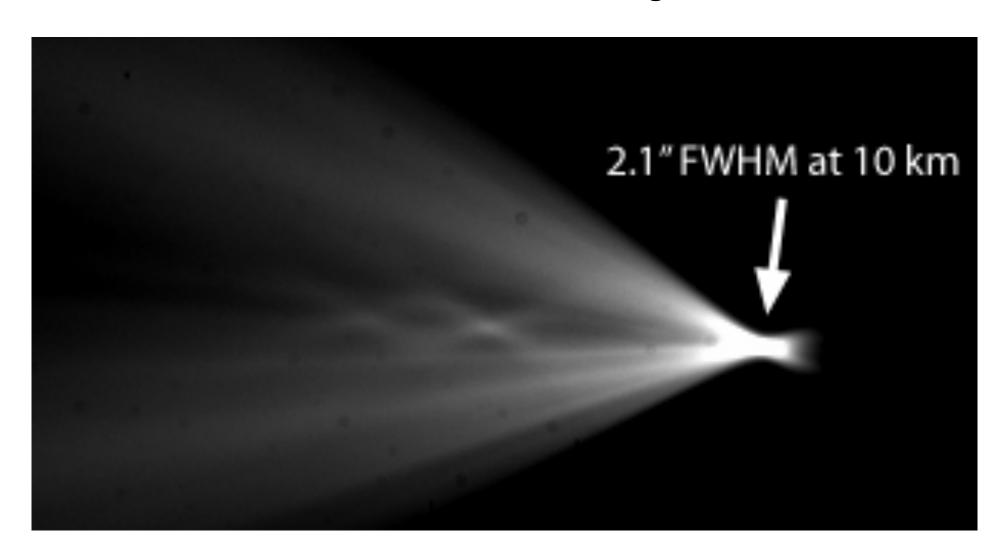
Laser Beam Projector



- JDSU commercial laser
 - 12 W @ 10 kHz, λ=355nm
 - Robust and reliable
- Uplink jitter correction with AO loop

Robo-AD UV Laser at the P60

• m_U ~ 8; 2.1" FWHM in 1.5" U seeing



Robo-AD Laser Operations

- First day setup
 - Purge air from cooling system, clean filter
 - Coolant is water (with a touch of propylene glycol in winter)
 - Focus laser system on sky
 - Temperature sensitive projector
 - Recenter laser pointing
 - Very rare
- Beginning of night
 - Ready to lase when turned on
 - ~15 minutes to stabilize (~18C laser head, ~10C cooling)

Robo-AD Laser Operations

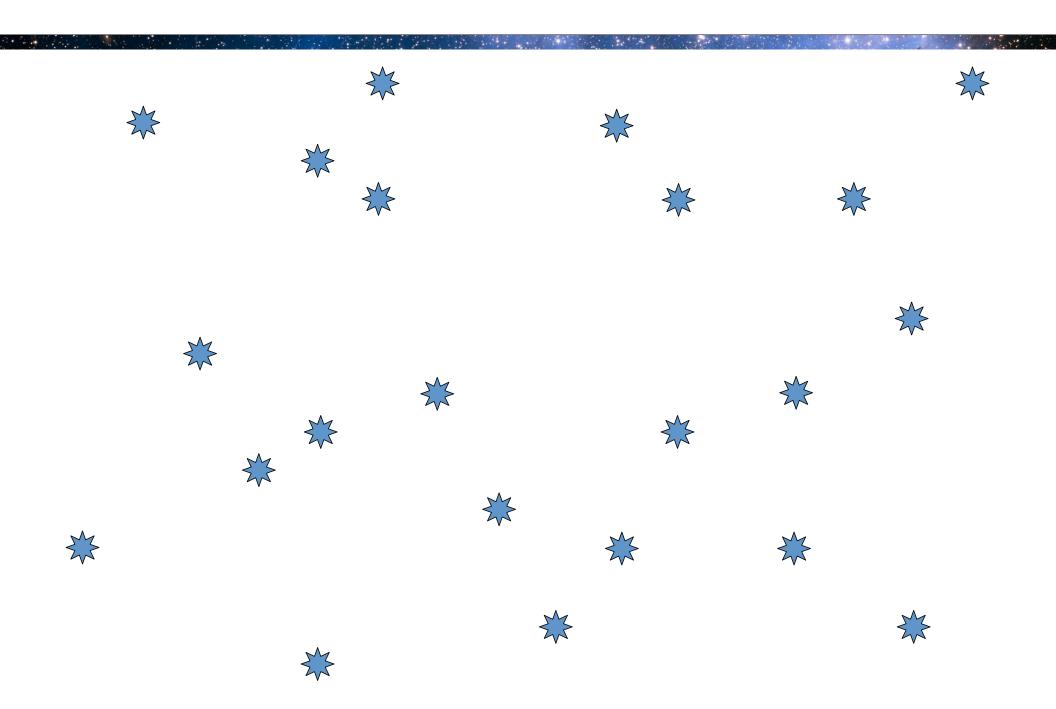
- At each pointing
 - Propagate laser after telescope pointing
 - Automated spiral search to center laser in WFS
 - Switch range gate off/on twice for backgrounding
 - Run through exposure, shutter before slew
- Laser does this ~250 times per night
 - Very robust, have had essentially no problems
- Safety system ensures laser cannot propagate unless telescope is in position, closure window is opened

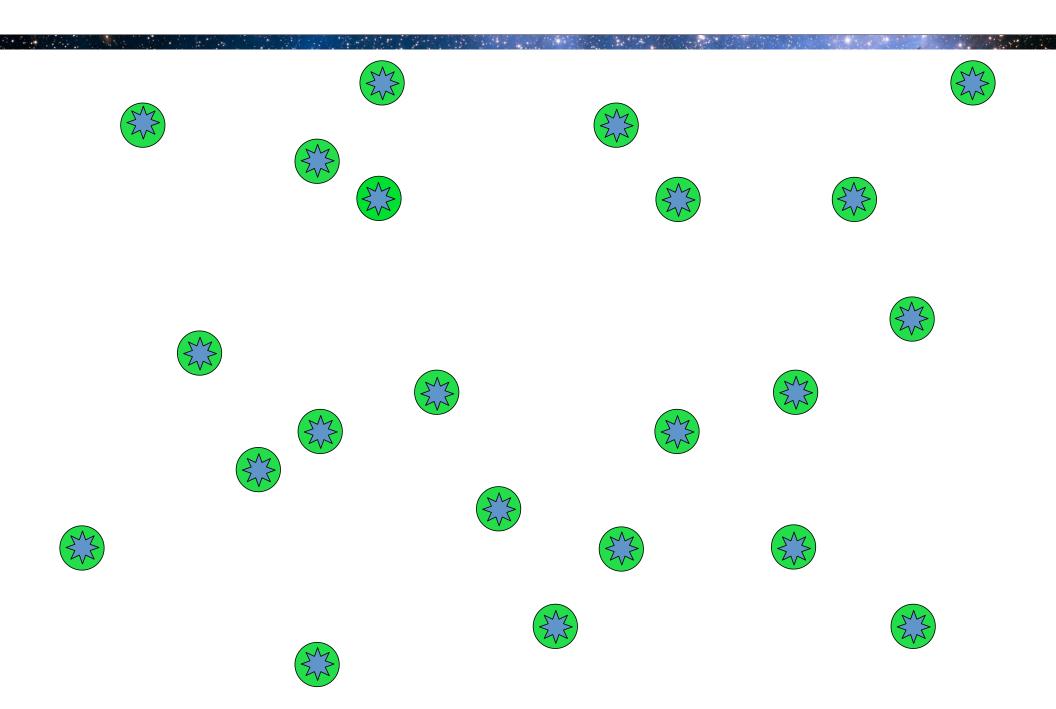
Queue Scheduler

- Intelligent system, decides based on priority
 - Priority calculated "on the fly"
- Large set of science programs
 - 30+ science programs
 - 10,000+ science targets

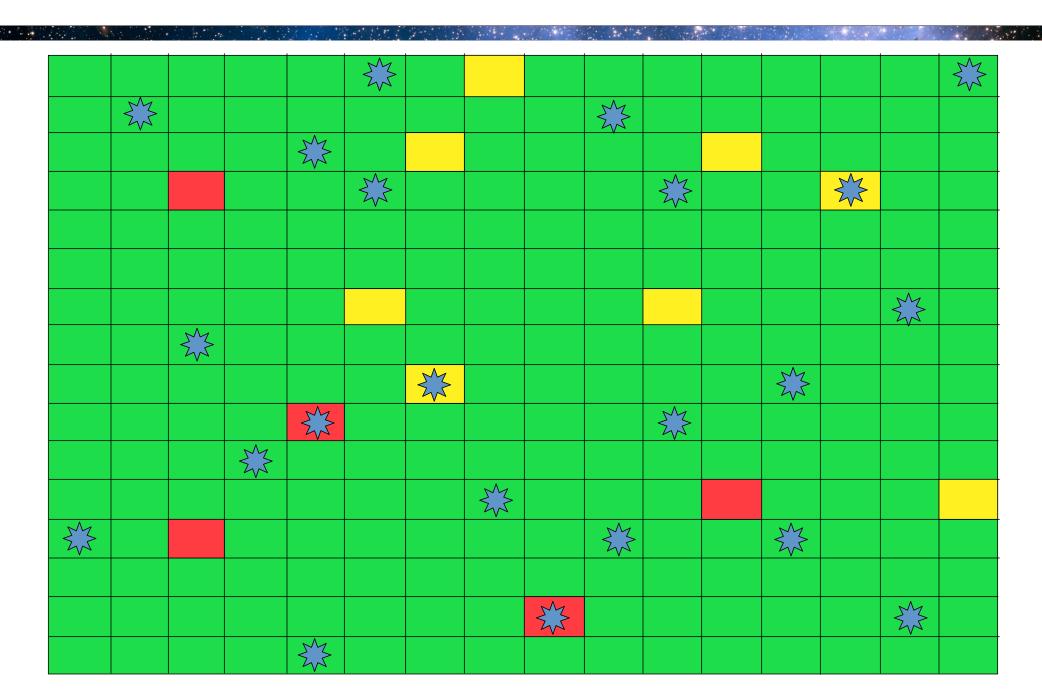
- Robotic systems benefit from all sky observing
 - Need capability to observe anywhere at any time

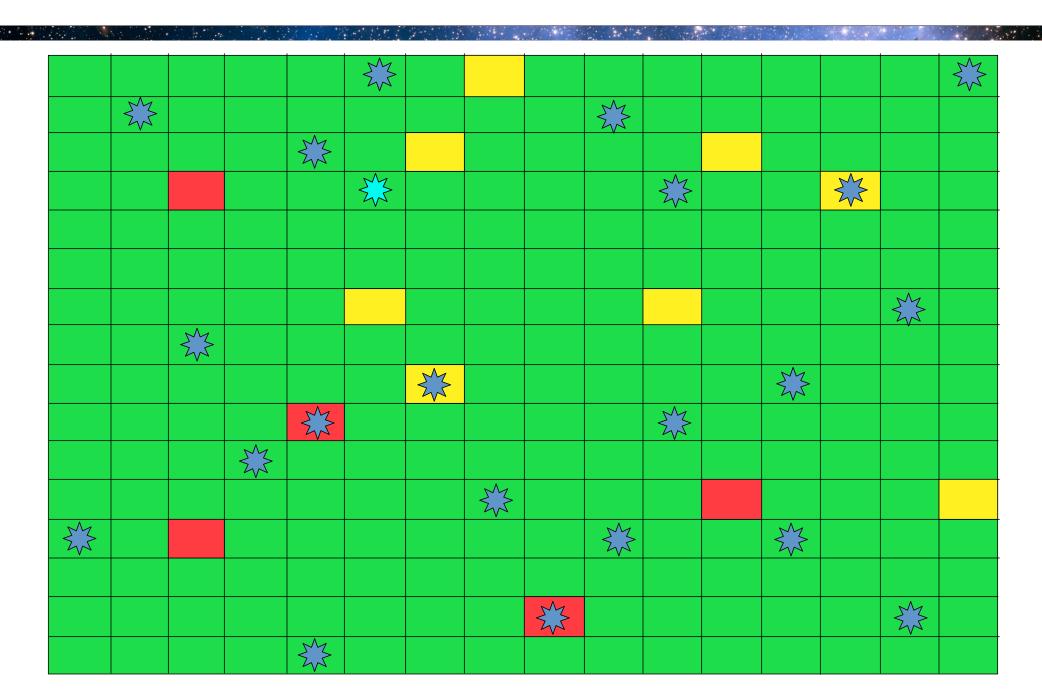
- US based LGS operators interface with USSTRATCOM
 - Provide satellite avoidance information
 - Observatories usually use RA, Dec based targets
 - Less than 100 targets per night
- Robo-AO is unusual
 - We requested ~1500 targets!
- We developed a new azimuth-elevation based strategy
 - Based on USSTRATCOM azimuth-elevation windows
 - Allows all-sky observations at almost any time

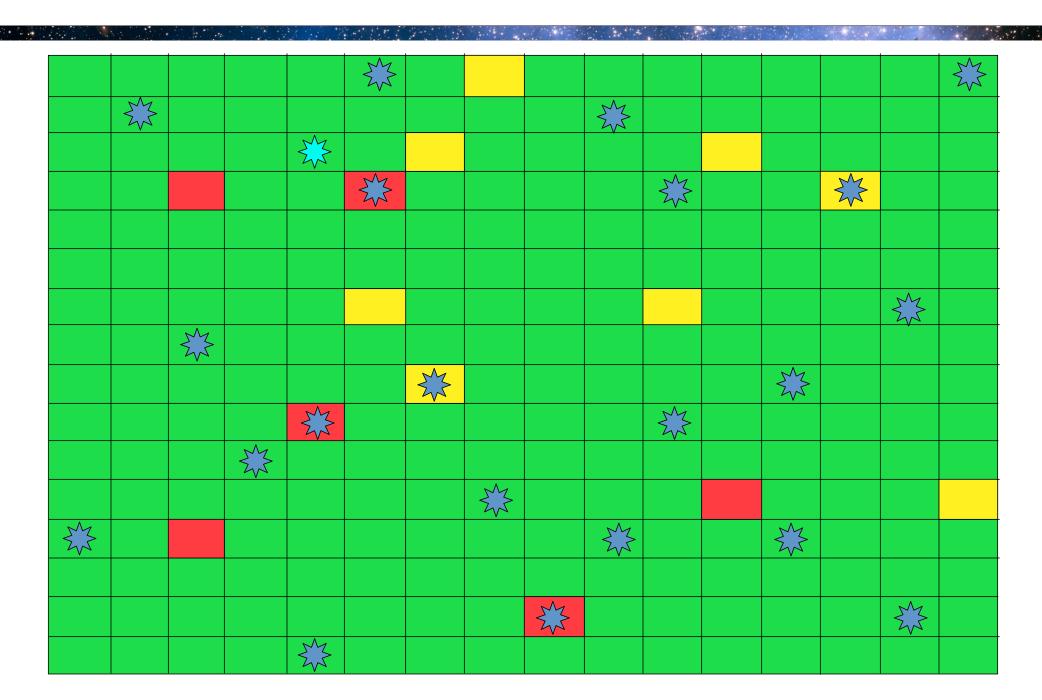


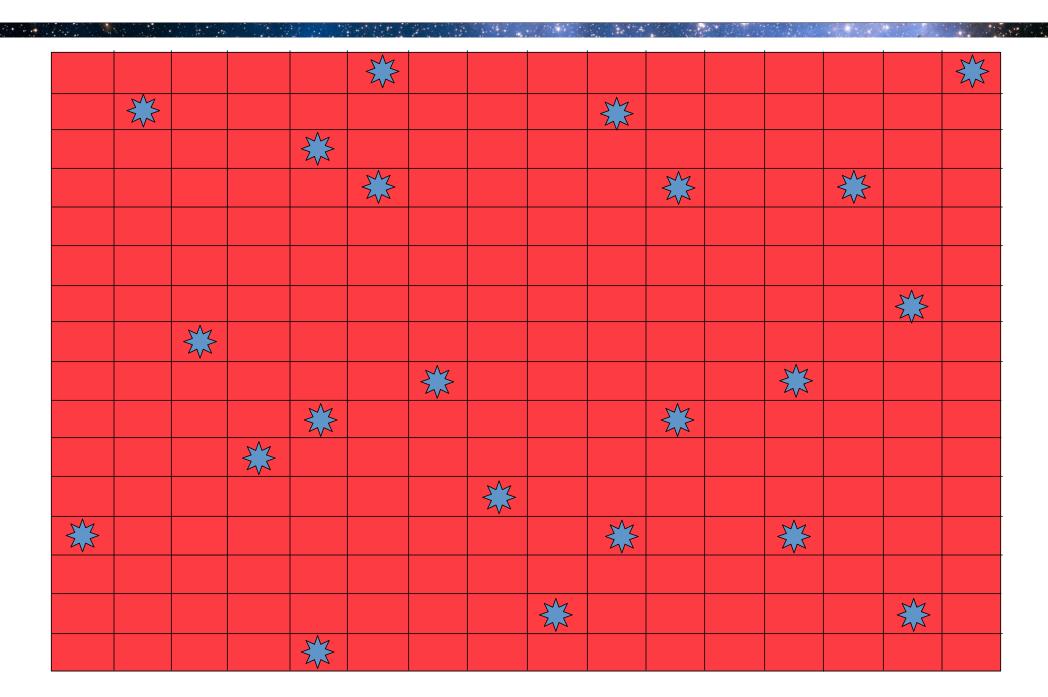


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- Successful operation for ~1.5 years
 - Closure windows are "essentially invisible"
- Automated interaction with new space-track.org website
 - Under development
- Upgrading Keck USSTRATCOM interaction with Robo-FD system
 - Target of opportunity observations only
- Plan to provide code to LGS community

